

Your solutions should be handed in *before* start of the lecture on the due date. Given $x = x(t)$, note the following notational equivalences: $dx/dt = x' = \dot{x}$ and $d^2x/dt^2 = x'' = \ddot{x}$.

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1. The following linear differential equation describes a forced, harmonic oscillator:

$$\ddot{x} + \omega^2 x = Ft,$$

where ω^2 and F are positive constants and with the initial condition $x(0) = 0$ and $\dot{x}(0) = 0$.

- (i) What are the units of F ?
- (ii) What is the homogeneous solution to the given equation? What is the particular solution?
- (iii) Now, what is the solution subject to the given initial condition?
- (iv) Sketch the solution. Describe what is happening.

2. The following differential equation describes a periodically forced, harmonic oscillator:

$$\ddot{x} + \omega^2 x = G \sin \Omega t,$$

where ω^2 , G and Ω are positive constants and with the initial condition $x(0) = 0$ and $\dot{x}(0) = 0$.

- (i) What is the homogeneous solution to the given equation? What is the particular solution?
- (ii) Now, what is the solution subject to the given initial condition?
- (iii) Describe what happens when $\omega = \Omega$; what happens to x ?
- (iv) What happen at early times, when $\Omega t \ll 1$; how does x behave with t at early times? [Hint: go to third order in small Ωt .]

3. Given $\hat{\mathbf{r}} = \cos \theta \hat{\mathbf{i}} + \sin \theta \hat{\mathbf{j}}$ and $\hat{\theta} = -\sin \theta \hat{\mathbf{i}} + \cos \theta \hat{\mathbf{j}}$, where $\theta = \theta(t)$,

- (i) Show that $\dot{\hat{\mathbf{r}}} = \dot{\theta} \hat{\theta}$ and $\dot{\hat{\theta}} = -\dot{\theta} \hat{\mathbf{r}}$.
- (ii) Using the definition of the position vector, $\mathbf{r} = r \hat{\mathbf{r}}$, show that $\mathbf{v} = \dot{r} \hat{\mathbf{r}} + r \dot{\theta} \hat{\theta}$, where \mathbf{v} is the velocity.
- (iii) Show that $\mathbf{a} = (\ddot{r} - r \dot{\theta}^2) \hat{\mathbf{r}} + (2\dot{r} \dot{\theta} + r \ddot{\theta}) \hat{\theta}$, where \mathbf{a} is the acceleration.
- (iv) Using the acceleration given in part (iii), show that uniform circular motion with constant angular velocity (i.e., $\dot{\theta} = \text{const.}$ and $r = \text{const.}$) leads to the centripetal acceleration, $\mathbf{a}_c = -(v_\theta^2/r) \hat{\mathbf{r}}$, where $v_\theta = r \dot{\theta}$ is the tangential speed.

[continued on the next page..]

4. A hanging pendulum consists of a mass m and a massless rigid rod of length l . There is gravity \mathbf{g} , which points straight down; but, the pendulum is *not* forced by any other external agencies.

(i) Sketch the situation when the mass is displaced by an angle θ in the counter-clockwise direction. Be sure to indicate the forces involved.

(ii) Using the results of Question 3, show that the governing equation of motion can be written as:

$$\ddot{\theta} + \frac{g}{l} \sin \theta = 0.$$

[N.B., l is a constant, since the rod is rigid.]

(iii) Show that for small displacement angle, the equation in part (ii) can be written as:

$$\ddot{\theta} + \omega^2 \theta = 0,$$

where $\omega^2 = g/l$.

(iv) Write down the general solution to the equation in part (iii).