

MAS' 226, 2007 MIDTERM SOLUTIONS

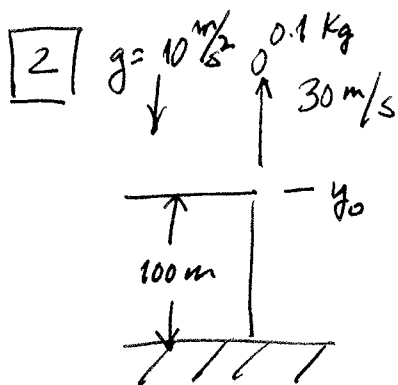
$$\boxed{1} \quad \vec{A} = (-xy, 1, 0), \quad \vec{B} = (-y, y^2, z)$$

$$a) \quad \vec{A} \cdot \vec{B} = xy^2 + y^2 = \boxed{y^2(x+1)}$$

$$b) \quad \vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -xy & 1 & 0 \end{vmatrix} = (0, 0, x) = \boxed{x \hat{k}}$$

$$c) \quad \vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0, \text{ since } \vec{\nabla} \perp (\vec{\nabla} \times \vec{B})$$

$$\text{or, } \vec{\nabla} \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & y^2 & z \end{vmatrix} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (0, 0, 1) = \boxed{0}$$



$$a) \quad 0 = v_0 - gt \Rightarrow t = \frac{v_0}{g} \Rightarrow y - y_0 = v_0 t - \frac{1}{2} g t^2$$

$$\Rightarrow y - y_0 = \frac{v_0^2}{g} - \frac{1}{2} g \frac{v_0^2}{g^2} = \frac{v_0^2}{2g}$$

$$\Rightarrow y - y_0 = \frac{30^2}{2 \cdot 10} = \frac{900}{20} = \boxed{45 \text{ m}}$$

b) time to reach max. height from y_0 = time to reach y_0 , dropping from y (which we can set to 0 without loss of generality):

$$\text{hence, } y - y_0 = -\frac{1}{2} g t^2 \Rightarrow t_d = \sqrt{\frac{2y}{g}} = \sqrt{\frac{90}{10}} = 3 \text{ s. Therefore, the ball has been up for } \boxed{6 \text{ s}}.$$

$$c) \quad \text{Since all of the kinetic energy comes from the initial potential energy through conversion, } mgh = \frac{1}{10} \cdot 10 \cdot 145 = \boxed{145 \text{ J}}$$

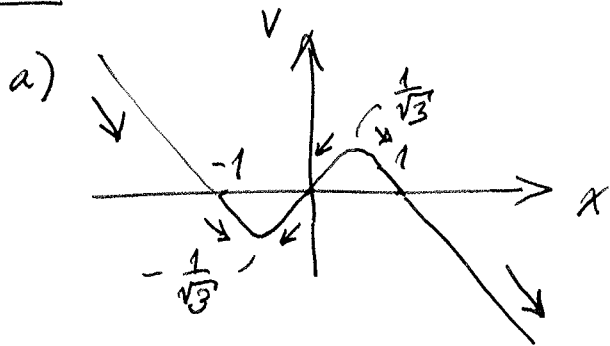
3

- a) A mass stays at rest or is in uniform motion unless acted upon by an external force.
- b) Two masses, m_1 and m_2 , are attracted along the line joining them by the force, $G \frac{m_1 m_2}{r^2} \hat{r}$, where r is the distance between the two masses, \hat{r} the direction of the position vector between them and G is a constant.
- c) The gravitational law is purely an attractive force law, whereas Coulomb's law is both attractive and repulsive (depending on the sign of the charge).

→ other possible answers:

- the constants of proportionality, G and K (in $\vec{F}_c = K \frac{q_1 q_2}{r^2} \hat{r}$) are different.
- the gravitational law acts on the masses, whereas Coulomb's law on charges

4 $V(x) = -x(x-1)(x+1)$



equilibrium pts:

$$V = -x(x^2 - 1) = x - x^3$$
$$\frac{dV}{dx} = 1 - 3x^2 = 0 \Rightarrow 3x^2 = 1$$
$$\Rightarrow \boxed{x = \pm \frac{1}{\sqrt{3}}}$$

b) $\frac{d^2V}{dx^2} = -6x \Rightarrow \begin{cases} x = \frac{1}{\sqrt{3}} \Rightarrow \frac{d^2V}{dx^2} = -\frac{6}{\sqrt{3}} < 0 \Rightarrow \text{local max (unstable)} \\ x = -\frac{1}{\sqrt{3}} \Rightarrow \frac{d^2V}{dx^2} = \frac{6}{\sqrt{3}} > 0 \Rightarrow \text{local min (stable)} \end{cases}$

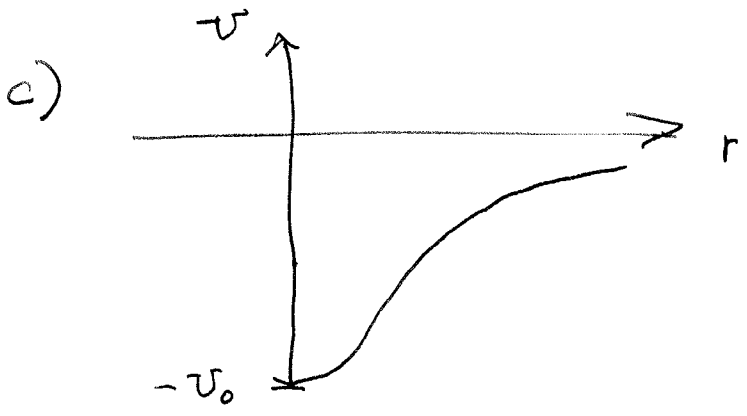
c) Use $\vec{F} = -\frac{dV}{dx} \hat{i}$. see sketch above.

5 $U(x,y,z) = -U_0 e^{-(x^2+y^2+z^2)}$

a) $\vec{F} = -\vec{\nabla}U = -\left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \cdot -U_0 e^{-(x^2+y^2+z^2)}$
 $= U_0 \cdot -2(x,y,z) \cdot e^{-(x^2+y^2+z^2)}$
 $= -2U_0 e^{-(x^2+y^2+z^2)} \underset{(x,y,z)}{=} \boxed{2U(x,y,z) = 2U\vec{r}}$

b) \vec{F} is conservative by construction, since

$\vec{\nabla} \times \vec{F} = -\vec{\nabla} \times \vec{\nabla}U = 0$



To get out of the center, we need U_0 amount of energy.